# Colored Particle Systems on the Ring: Stationarity from Yang-Baxter equation 

Leonid Petrov<br>(University of Virginia)<br>October 6, 2023<br>ASEP workshop at SCGP

# Multispecies ASEP and its stationary measure 

(Results)

## Colored ASEP (multispecies ASEP, mASEP)



- Particles have colors (types) in $\{1, \ldots, n\}$.
- Particles of colors $\left(i_{k}, i_{k+1}\right)$ at adjacent sites
$k, k+1$ swap at rate (color $n$ : highest priority)
$\operatorname{Rate}\left(\left(i_{k}, i_{k+1}\right) \rightarrow\left(i_{k+1}, i_{k}\right)\right)= \begin{cases}q, & i_{k}>i_{k+1} \\ 1, & i_{k}<i_{k+1}\end{cases}$
- $q \in[0,1)$ is the parameter
- Lives on a ring with $N$ sites; there are $N_{i}$
particles of color $i$ (conserved quantities)


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- There is a unique stationary distribution

$\operatorname{Prob}_{N_{1}, \ldots, N_{n}}\left(\eta_{1}, \ldots, \eta_{N}\right)$ in each "sector"

$$
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- For $n=1$ (single color), it is uniform among all $\binom{N}{N_{1}}$ configurations
- For many colors, nontrivial correlations
- Multiline queues: [Angel 2006], [Ferrari-Martin 2007] (mTASEP, $q=0$ ), [Martin 2018] (full mASEP)
- Matrix Ansatz: [Prolhac-Evans-Mallick 2009]
- Macdonald polynomials: [Cantini-de Gier-Wheeler 2015], [Corteel-Mandelshtam-Williams 2018]
- We use integrable vertex models


## Main result for mASEP [Aggarwal-Nicoletti-P. 2023]

- We define a vertex model on the cylinder $\{-n,-n+1, \ldots,-2,-1\} \times(\mathbb{Z} / N \mathbb{Z})$
- The mASEP configuration $\eta=\left(\eta_{1}, \ldots, \eta_{N}\right)$ encodes the boundary condition.
- $\operatorname{Prob}_{N_{1}, \ldots, N_{n}}\left(\eta_{1}, \ldots, \eta_{N}\right)$ is proportional to the partition function with the boundary $\eta$, which involves the summation over the wrappings $\mathbf{M}(-n), \ldots, \mathbf{M}(-1)$. There are infinitely many arrows of color $m$ wrapping around column ( $-m$ ).
- Weights are denoted by $\mathbb{W}_{s, x}^{(-m)}(\mathbf{A}, k ; \mathbf{C}, \ell)$, $\mathbf{A}, \mathbf{C} \in \mathbb{Z}_{\geq 0}^{n}, k, \ell \in\{0,1, \ldots, n\}$




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|  | $\left(x-s q^{A_{k}}\right) q^{\mathbf{A}_{[k+1, n]}}$ |  | $x q^{\mathbf{A}_{[m+1, n]}}$ |
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- Similar result on the line (with fewer parameters for positivity). The remaining parameters are responsible for the color densities.


Matching to previous results

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| :---: | :---: | :---: | :---: |
|  <br> 1 |  |  |  $s q^{\mathbf{A}_{[m+1, n]}}$ |

$$
\mathbf{M}(-4) \quad \mathbf{M}(-3) \quad \mathbf{M}(-2) \quad \mathbf{M}(-1)
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- The vertex model for $s=0, x=1$ is essentially the Matrix Product Ansatz (MPA) solution [Prolhac-EvansMallick 2009]. The matrices are row partition functions:

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- We can use row-dependent $x_{j}$ and weighted wrappings to produce nonsymmetric Macdonald polynomials like [Cantini-de Gier-Wheeler 2015], [Corteel-Mandelshtam-Williams 2018]; apparently different from [Borodin-Wheeler 2019]

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exponential clock with rate
$x_{k}^{-1}\left(1-q^{\left.\mathbf{V}(k)_{i}\right)} q^{\mathbf{V}(k)_{[i+1, n]} \text {. }}\right.$
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- Colored q-PushTASEP of capacity P
- [Borodin-Wheeler 2018], [Bukh-Cox 2019], [Angel-Ayyer-Martin, in progress 2023]
- A particle activates with rate $x_{k}^{-1}\left(q^{-A_{j}}-1\right) q^{\mathrm{P}-A_{[j+1, n]}}$
- Active particle hops from site to site, where it can either stop; stop activate another particle of lower color; or move through, with prob.

$$
1-q^{\mathrm{P}-|\mathbf{B}|},\left(q^{-B_{d}}-1\right) q^{\mathrm{P}-B_{[d+1, n]},} q^{\mathrm{P}-B_{[c, n]}}
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## Stationarity from Yang-Baxter equation

"Toy" example: stationarity for the single-color stochastic six-vertex model in the quadrant
(Explain the main idea in a simpler setting than the ring)
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The weights with $a_{1}=a_{2}=1, b_{1}=\delta_{1}, c_{1}=1-\delta_{1}, b_{2}=\delta_{2}$, $c_{2}=1-\delta_{2}$ are stochastic: $\sum_{i_{2}, j_{2}} w\left(i_{1}, j_{1} ; i_{2}, j_{2}\right)=1$.
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$\delta_{1}, \delta_{2} \rightarrow 0$ and $q$ stays fixed (so, $u \rightarrow 1$ )

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- Stationarity. Assume that the boundary conditions are Bernoulli with densities $\rho_{h}, \rho_{v}$.
Then for $\rho_{h}=\frac{u \rho_{v}}{1-\rho_{v}+u \rho_{v}}$, the distribution is
stationary in the quadrant.

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The weights with $a_{1}=a_{2}=1, b_{1}=\delta_{1}, c_{1}=1-\delta_{1}, b_{2}=\delta_{2}$, $c_{2}=1-\delta_{2}$ are stochastic: $\sum_{i_{2}, j_{2}} w\left(i_{1}, j_{1} ; i_{2}, j_{2}\right)=1$.

Converges to ASEP along the diagonal as
$\delta_{1}, \delta_{2} \rightarrow 0$ and $q$ stays fixed (so, $u \rightarrow 1$ )


$$
\stackrel{\rho_{v}\left(1-\rho_{n}\right)}{\uparrow} \stackrel{\rho}{i}^{\rho_{n}\left(1-\rho_{v}\right)\left(1-\delta_{2}\right)}+\prod^{\rho_{v}\left(1-\rho_{n}\right) \delta_{1}}
$$

- Stationarity. Assume that the boundary conditions are Bernoulli with densities $\rho_{h}, \rho_{v}$.
Then for $\rho_{h}=\frac{u \rho_{v}}{1-\rho_{v}+u \rho_{v}}$, the distribution is stationary in the quadrant.


"Toy" example: stationarity for the single-color stochastic six-vertex model



[Gwa-Spohn 1992], [Borodin-Corwin-Gorin 2014], [Aggarwal-Borodin 2016]

$$
u:=\frac{1-\delta_{1}}{1-\delta_{2}}, \quad q:=\delta_{1} / \delta_{2}
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The weights with $a_{1}=a_{2}=1, b_{1}=\delta_{1}, c_{1}=1-\delta_{1}, b_{2}=\delta_{2}$, $c_{2}=1-\delta_{2}$ are stochastic: $\sum_{i_{2}, j_{2}} w\left(i_{1}, j_{1} ; i_{2}, j_{2}\right)=1$.

Converges to ASEP along the diagonal as
$\delta_{1}, \delta_{2} \rightarrow 0$ and $q$ stays fixed (so, $u \rightarrow 1$ )


$$
\begin{aligned}
& \rho_{v}\left(1-\rho_{h}\right) \quad \rho_{h}\left(1-\rho_{v}\right)\left(1-\delta_{2}\right) \\
& \hat{\rho}^{\rho}+\cdots \cdots \\
& \rho_{v}\left(1-\rho_{h}\right)
\end{aligned}
$$


"Toy" example: stationarity for the single-color stochastic six-vertex model

$$
\begin{array}{cccccccc}
\vdots & & & - & \vdots & & \\
\hdashline & - & & - & - \\
1 & 1 & \delta_{1} & \delta_{2} & 1-\delta_{1} & 1-\delta_{2}
\end{array}
$$

$$
\rho_{h}=\frac{u \rho_{v}}{1-\rho_{v}+u \rho_{v}} \quad u:=\frac{1-\delta_{1}}{1-\delta_{2}}, \quad q:=\delta_{1} / \delta_{2}
$$

- Yang-Baxter equation. For fixed $q$, and fixed $i_{1}, i_{2}, i_{3} \in\{0,1\}$, the joint distribution of $j_{1}, j_{2}, j_{3}$ in two pictures is the same:

"Toy" example: stationarity for the single-color stochastic six-vertex model

[Gwa-Spohn 1992], [Borodin-Corwin-Gorin 2014], [Aggarwal-Borodin 2016]
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$$
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$\rho_{h}=\frac{u \rho_{v}}{1-\rho_{v}+u \rho_{v}} \quad u:=\frac{1-\delta_{1}}{1-\delta_{2}}, \quad q:=\delta_{1} / \delta_{2}$

- Fusion [Kulish-Reshetikhin-Sklyanin 1983], [Corwin-P. 2015] - a way to construct new YBE solutions from existing ones.

"Toy" example: stationarity for the single-color stochastic six-vertex model
$\rho_{h}=\frac{u \rho_{v}}{1-\rho_{v}+u \rho_{v}} \quad u:=\frac{1-\delta_{1}}{1-\delta_{2}}, \quad q:=\delta_{1} / \delta_{2}$
- Fusion [Kulish-Reshetikhin-Sklyanin 1983],
[Corwin-P. 2015] - a way to construct new YBE
 solutions from existing ones.

$\frac{1-x q^{g}}{1+x}$

$$
\frac{x\left(1-q^{g}\right)}{1+x}
$$

$$
\frac{x}{1+x}
$$

$$
\frac{1}{1+x}
$$


"Toy" example: stationarity for the single-color stochastic six-vertex model

$$
\rho_{h}=\frac{u \rho_{v}}{1-\rho_{v}+u \rho_{v}} \quad u:=\frac{1-\delta_{1}}{1-\delta_{2}}, \quad q:=\delta_{1} / \delta_{2}
$$

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$$
\frac{1-x q^{g}}{1+x}
$$

$$
\frac{x\left(1-q^{g}\right)}{1+x}
$$

$$
\frac{x}{1+x} \quad \frac{1}{1+x}
$$




## Stationarity via Yang-Baxter

- For $g=+\infty$, the right output of the fat vertex is $\operatorname{Bernoulli}\left(\frac{x}{x+1}\right)$, independent of the bottom and the left inputs.
- The Yang-Baxter equation is equivalent to the previous "Burke" computation: $\rho_{v}=\frac{x}{x+1}$,

$$
\rho_{h}=\frac{u x}{u x+1} \Rightarrow \rho_{h}=\frac{u \rho_{v}}{1-\rho_{v}+u \rho_{v}}
$$

"Toy" example: stationarity for the single-color stochastic six-vertex model

$$
\begin{array}{cccccc}
:- & & - & - & \frac{1}{1} & \cdots \\
1 & 1 & \delta_{1} & \delta_{2} & 1-\delta_{1} & 1-\delta_{2} \\
\rho_{h}=\frac{u \rho_{v}}{1-\rho_{v}+u \rho_{v}} & u:=\frac{1-\delta_{1}}{1-\delta_{2}}, \quad q:=\delta_{1} / \delta_{2}
\end{array}
$$

"Toy" example: stationarity for the single-color stochastic six-vertex model

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$$
\rho_{h}=\frac{u \rho_{v}}{1-\rho_{v}+u \rho_{v}} \quad u:=\frac{1-\delta_{1}}{1-\delta_{2}}, \quad q:=\delta_{1} / \delta_{2}
$$


$\frac{1-x q^{g}}{1+x} \quad \frac{x\left(1-q^{q}\right)}{1+x}$

"Toy" example: stationarity for the single-color stochastic six-vertex model


# Stationarity from Yang-Baxter equation 

Colored stochastic six-vertex model in the quarter plane

Colored stochastic six-vertex model. Many colors $\Rightarrow$ many fat lines


Colored stochastic six-vertex model. Many colors $\Rightarrow$ many fat lines


- Fusion and Yang-Baxter equation.

Colored stochastic six-vertex model. Many colors $\Rightarrow$ many fat lines


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Colored stochastic six-vertex model. Many colors $\Rightarrow$ many fat lines


- Fusion and Yang-Baxter equation.

Higher spin, higher rank stochastic weights. Related to $U_{q}\left(\widehat{s l}{ }_{n+1}\right) ; 1 \leq k<\ell \leq n$


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Related to $U_{q}\left(\widehat{s l}{ }_{n+1}\right) ; 1 \leq k<\ell \leq n$


- Set the number of arrows of a given color $m$ to $+\infty$. We get $\mathbb{W} \mathbb{S}_{s_{m}}^{(-m)}$ 响 from the beginning (up to simple factors).

Colored stochastic six-vertex model. Many colors $\Rightarrow$ many fat lines
Red > Green


- Fusion and Yang-Baxter equation.

Higher spin, higher rank stochastic weights.
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- Set the number of arrows of a given color $m$ to $+\infty$. We get $\mathbb{W}_{s_{m}, x_{m}}^{(-m)}$ from the beginning (up to simple factors).

Colored stochastic six-vertex model. Many colors $\Rightarrow$ many fat lines


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Related to $U_{q}\left(\widehat{s l}{ }_{n+1}\right) ; 1 \leq k<\ell \leq n$


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Colored stochastic six-vertex model. Many colors $\Rightarrow$ many fat lines Red > Green


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## Stationarity from Yang-Baxter equation

mASEP on the ring

Yang-Baxter equation on the $n \times N$ cylinder

(These weights are not stochastic and have more parameters than on the line; all of this is okay on the ring)

Yang-Baxter equation on the $n \times N$ cylinder

(These weights are not stochastic and have more parameters than on the line; all of this is okay on the ring)

Yang-Baxter equation on the $n \times N$ cylinder


|  <br> 1 |  |  | $x q^{\mathbf{A}_{[m+1, n]}}$ |
| :---: | :---: | :---: | :---: |
|  <br> 1 |  |  |  |

(These weights are not stochastic and have more parameters than on the line; all of this is okay on the ring)


Yang-Baxter equation on the $n \times N$ cylinder


|  <br> 1 |  $\left(x-s q^{A_{k}}\right) q^{\mathbf{A}_{[k+1, n]}}$ |  |  $x q^{\mathbf{A}_{[m+1, n]}}$ |
| :---: | :---: | :---: | :---: |
|  | $x\left(1-q^{A_{\ell}}\right) q^{\mathbf{A}_{[\ell+1, n]}}$ | $s\left(1-q^{A_{k}}\right) q^{\mathbf{A}_{[k+1, n]}}$ | $s q^{\mathbf{A}_{[m+1, n]}}$ |

(These weights are not stochastic and have more parameters than on the line; all of this is okay on the ring)


Yang-Baxter equation on the $n \times N$ cylinder


|  <br> 1 |  $\left(x-s q^{A_{k}}\right) q^{\mathbf{A}_{[k+1, n]}}$ |  |  $x q^{\mathbf{A}_{[m+1, n]}}$ |
| :---: | :---: | :---: | :---: |
|  | $x\left(1-q^{A_{\ell}}\right) q^{\mathbf{A}_{[\ell+1, n]}}$ | $s\left(1-q^{A_{k}}\right) q^{\mathbf{A}_{[k+1, n]}}$ | $s q^{\mathbf{A}_{[m+1, n]}}$ |

(These weights are not stochastic and have more parameters than on the line; all of this is okay on the ring)

Commutation relation on the cylinder
$\sum \mathfrak{Q}(\emptyset, \eta) T_{y / x}\left(\eta, \eta^{\prime}\right)=T_{y / x}(\emptyset, \emptyset) \mathfrak{Q}\left(\emptyset, \eta^{\prime}\right)=\mathfrak{Q}\left(\emptyset, \eta^{\prime}\right)$


## Yang-Baxter equation on the $n \times N$ cylinder


(These weights are not stochastic and have more parameters than on the line; all of this is okay on the ring)

## Commutation relation on the cylinder

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(Bethe Ansatz: construct eigenvalue of $T$ as a partition function )


Limit to the mASEP, $y / x=1-\epsilon$, continuous time
mASEP limit $\delta_{1}, \delta_{2} \rightarrow 0, q=\delta_{1} / \delta_{2}$



Time $\sim \tau / \epsilon$

Limit to the mASEP, $y / x=1-\epsilon$, continuous time
mASEP limit $\delta_{1}, \delta_{2} \rightarrow 0, q=\delta_{1} / \delta_{2}$



Time $\sim \tau / \epsilon$

$$
\langle 1,4| \check{\mathfrak{R}}_{1-\epsilon}|4,1\rangle=R_{1-\epsilon}(1,4 ; 1,4)=\frac{\epsilon}{1-q}+O\left(\epsilon^{2}\right)
$$

Limit to the mASEP, $y / x=1-\epsilon$, continuous time
mASEP limit $\delta_{1}, \delta_{2} \rightarrow 0, q=\delta_{1} / \delta_{2}$


Time $\sim \tau / \epsilon$

$$
\langle 1,4| \check{\mathfrak{R}}_{1-\epsilon}|4,1\rangle=R_{1-\epsilon}(1,4 ; 1,4)=\frac{\epsilon}{1-q}+O\left(\epsilon^{2}\right)
$$

## Conclusions

- A lot of recent activity around stationary measures for colored (also called multi-species or multi-type) and monochrome interacting particle systems in different geometries (line, ring, half-space, segment).
- Motivated by asymptotic phenomena (microscopic characteristics, stationary measures for KPZ equation)
- Rich algebraic and combinatorial structure (e.g. nonsymmetric Macdonald polynomials)
- We show that the ring, line, and quadrant stationarity follow directly from the Yang-Baxter equation.
- Other geomeries?
- Box ball systems?
- Stationary horizons / speed processes?


Bonus: Matrix Product Ansatz from Yang-Baxter equation
Matrix Product Ansatz expression for the mASEP stationary measure

$$
\operatorname{Prob}_{N_{1}, \ldots, N_{n}}^{\mathrm{mASEP}}(\eta)=\frac{\operatorname{Trace}\left(X_{\eta_{1}}^{\mathrm{MPA}} \ldots X_{\eta_{N}}^{\mathrm{MPA}}\right)}{Z_{N_{1}, \ldots, N_{n}}^{\mathrm{MPA}}}
$$

## Bonus: Matrix Product Ansatz from Yang-Baxter equation

Matrix Product Ansatz expression for the mASEP stationary measure

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$$



Key identity in the stationarity proof: existence of auxiliary matrices in [Prolhac-Evans-Mallick 2009]

$$
\sum_{i, i^{\prime}=0}^{n} X_{i}^{\mathrm{MPA}} X_{i^{\prime}}^{\mathrm{MPA}}\left(\mathcal{M}_{l o c}\right)_{i i^{\prime}, j j^{\prime}}=X_{j}^{\mathrm{MPA}} \widehat{X}_{j^{\prime}}^{\mathrm{MPA}}-\widehat{X}_{j}^{\mathrm{MPA}} X_{j^{\prime}}^{\mathrm{MPA}}
$$

## Bonus: Matrix Product Ansatz from Yang-Baxter equation



Matrix Product Ansatz expression for the mASEP stationary measure

$$
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$$

## Yang-Baxter equation

$$
\begin{gathered}
\sum_{i, i^{\prime}=0}^{n} X_{i}^{\mathrm{MPA}}(u) X_{i^{\prime}}^{\mathrm{MPA}}(u(1-\epsilon)) \cdot R_{1-\epsilon}\left(i, i^{\prime} ; j^{\prime}, j\right)=X_{j}^{\mathrm{MPA}}(u(1-\epsilon)) X_{j^{\prime}}^{\mathrm{MPA}}(u) \\
\widehat{X}_{j}^{\mathrm{MPA}}(u):=(1-q) u \frac{\partial}{\partial u} X_{j}^{\mathrm{MPA}}(u)
\end{gathered}
$$

## Bonus: Matrix Product Ansatz from Yang-Baxter equation

$$
A D-q D A=E A-q A E=(1-q) A, \quad E D-q D E=(1-q)(E+D) .
$$

$A:=\left(\begin{array}{cccc}1 & s & 0 & \ldots \\ 0 & q & q s & \ldots \\ 0 & 0 & q^{2} & \ldots \\ \vdots & \vdots & \vdots & \ddots\end{array}\right), \quad D:=u^{-1}\left(\begin{array}{cccc}u-s & 0 & 0 & \ldots \\ 1-q & u-s q & 0 & \cdots \\ 0 & 1-q^{2} & u-s q^{2} & \cdots \\ \vdots & \vdots & \vdots & \ddots\end{array}\right)$,
$E:=\left(\begin{array}{cccc}1 & u & 0 & \ldots \\ 0 & 1 & u & \ldots \\ 0 & 0 & 1 & \ldots \\ \vdots & \vdots & \vdots & \ddots\end{array}\right)$.
$s=0$ : [Prolhac-Evans-Mallick 2009]
$s=q$ : conjectured alternative queues [Martin 2018]
General $s$ : interpolation

|  <br> 1 |  |  |  |
| :---: | :---: | :---: | :---: |
|  <br> 1 |  | $s \cdot\left(1-q^{A_{k}}\right) q^{A_{[k+1, n]}}$ | $s \cdot q^{A_{[m+1, n]}}$ |

## Thank you for attention!

## Special thanks to the organizers of the conference

